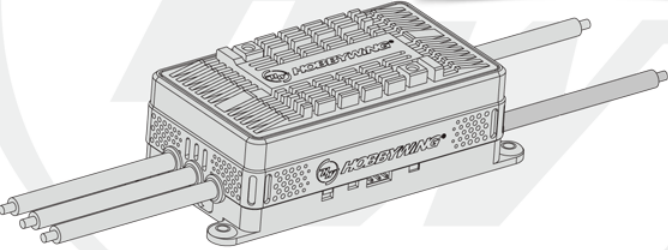


USER MANUAL

PLATINUM

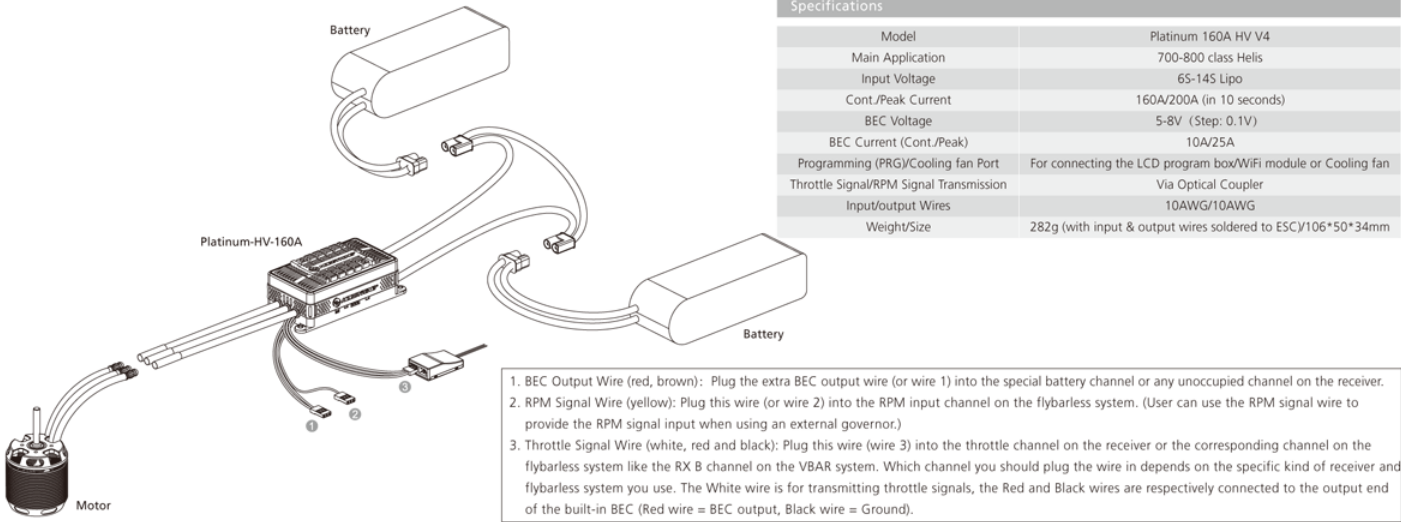
Brushless Electronic Speed Controller
Platinum HV-160A



- Multiple protections like thermal shutdown protection, overload protection, over-current protection, etc.
- BEC is separated from other circuits of the ESC, it will keep its normal output when the MOSFET board of the ESC is burnt down.
- Online firmware upgrade via HOBBYWING multifunction LCD program box or WiFi module.

02 Begin to Use the New Brushless ESC

1 Connections



2 Throttle Range Calibration

Attention! The default throttle range of this ESC is from 1100μs to 1940μs, so you need to re-calibrate the throttle range when the first time you use this ESC or after you replace the transmitter.

1.Connections before the Throttle Range Calibration: As shown above (Wiring Diagram 1)

2.ESC/Radio Calibration

Turn on the transmitter, move the throttle stick to the top position, and connect the ESC to a battery. The motor will emit “J123” indicating the ESC is powered on normally.

The ESC will keep beeping indicating the number of LiPo cells you have plugged in. (A long beep represents 5, a short beep represents 1. E.g. The ESC will beep two long beeps and two short beeps to indicate a 12S LiPo pack.

2 seconds later, the motor will emit two short beeps indicating the maximum throttle position has been successfully calibrated and accepted.

Move the throttle stick to the bottom position in 3 seconds. 1 second later, a short beep will emit indicating the minimum throttle position has been accepted.

ESC/radio calibration completed, the power system is ready to go.

ATTENTION!

During the ESC/Radio calibration, please set the throttle curve to NORMAL and ensure the corresponding throttle amounts to the maximum throttle endpoint and the minimum throttle endpoint on your transmitter are respectively 100% and 0%.

03 Programmable Item List

“*”in the form below indicate factory defaults.

Programmable Items	Parameter Values						
	Option 1	Option 2	Option 3	Option 4	Option 5	Option 6	Option 7
1. Flight Mode	Fixed-wing	Heli (Linear Throttle Response)	*Heli (Elf Governor)	Heli (Store Governor)			
2. LiPo Cells	*Auto Calculate	6S	8S	10S	12S	14S	
3. Voltage Cutoff Mode	*Soft	Hard					
4. Cutoff Voltage	2.7-3.7V (*3.3V)						
5. BEC Voltage	5-8V (*7.4V)						
6. Start-up Time	4-25s (*15s)						
7. Governor Parameter P	0-9 (*3)	You can increase the governor sensitivity (P, I) if you think the governor feel is weak. However, extreme high sensitivity will cause unstable RPM. To be specific, the RPM will float up/down around the preset value.					
8. Governor Parameter I	0-9 (*5)						
9. Auto Restart Time	0-90s (*25s)						
10. Timing	0-30° (*15°)						
11. PWM Frequency	8Khz	15Khz	20Khz	*30Khz			
12. Brake Force/Amount	0-100% (*0)						
13. Motor Rotation	CW	CCW					
14. Restart Acceleration Time	1s	1.5s	*2s	2.5s	3s		
15. Con.Freewheel	Activate	Disable	This item can only be disabled in Fix-wing mode and Heli (Linear Throttle Response) mode.				



Thank you for purchasing this HOBBYWING product! Brushless power systems can be very dangerous. Any improper use may cause personal injury and damage to the product and related devices. We strongly recommend reading through this user manual before use. Because we have no control over the use, installation, or maintenance of this product, no liability may be assumed for any damages or losses resulting from the use of the product. We do not assume responsibility for any losses caused by unauthorized modifications to our product.

01 Features

- High performance microprocessor with a running frequency of up to 120MHz for excellent motor speed-governing and super soft startup.
- Microprocessor powered by independent DC regulator has better anti-interference performance, which greatly reduces the risk of losing control.
- The maximum motor speed can reach 210000 RPM (for 2 pole motor), 70000 RPM (for 6 pole motor) and 35000 RPM (for 12 pole motor).
- Multiple flight modes: Fixed-wing, Heli (Linear Throttle Response), Heli (Elf Governor), and Heli (Store Governor).
- Data logging records the standardized RPM, minimum voltage, maximum current and maximum temperature of the flight.
- “Restart in auto rotation” can manually interrupt the auto rotation and quickly restart the motor to avoid crashes caused by incorrect operations.
- WiFi module (sold separately) for programming the ESC wirelessly with your smart phone (ios or Android).
- Internal anti-spark circuitry effectively eliminates electric sparks produced when the ESC is powered on.
- Independent output port for RPM (that is: motor speed) signals.
- Separate programming port for ESC programming or parameter setting.

04 Explanations for Programmable Items

1. Flight Mode

1.1 In “Fixed Wing” mode, the motor will start up when the throttle amount reaches 5% or above. There is no soft start-up, the motor responds to the throttle increase rapidly.

1.2 In “Heli (Linear Throttle Response)” mode, the motor will start up in a very soft way when the throttle amount reaches 5% or above. And it will accelerate to the RPM corresponds to the specific throttle amount in the preset start-up time (4~25s).

1.3 In “Heli (Elf Governor)” mode, the motor will start up when the throttle amount reaches 40% or above, it will start up in a very soft way. And it will complete the speed standardization and enter the speed-governing operation in the preset start-up time. In this mode, the motor will standardize its speed every time it starts up. Due to different discharge rates/capabilities of different batteries, the RPM you standardize each time may be a little different. In consequence, at the same throttle amount, the RPM may be a bit different when using different batteries.

1.4 In “Heli (Store Governor)” mode, the motor will start up when the throttle amount reaches 40% or above. It will also start up in a very soft way. And it will also complete the speed standardization and enter the speed-governing operation in the preset start-up time. In this mode, the motor will only standardize its speed the first time when it starts up. When performing RPM standardization for the first time, we recommend using a fully-charged battery with good discharge capability. After the RPM standardization, while you change another battery to fly your aircraft, at the same throttle amount, the RPM will always be the same as the RPM of the first flight. For consistent control feel, we recommend using this mode.

Explanations for RPM Standardization

1.1.The motor will enter the soft start-up when user switches the throttle amount from 0 to 40% or above (50% throttle is recommended). The pitch of main blades should be 0 degree during the soft start-up process, the RPM standardization completes when the soft start-up ends, and the ESC enters the speed-governing state. In “Heli (Store Governor)” mode, if user wants to re-standardize the speed, he needs to set the flight mode to “Heli (Elf Governor)” and save this mode first, and then reset the flight mode back to “Heli (Store Governor)”, then the ESC will re-standardize the motor speed when the motor rotates for the first time after the ESC is re-powered on.

1.2. For ensuring the speed-governing effect, we recommend setting the throttle amount to 90% or below in both speed-governing modes (Heli Store Governor & Heli Elf Governor), so there will be sufficient compensating room to maintain the consistency of the RPM. We recommend replacing the motor or adjusting the gear ratio if the expected RPM still cannot be reached when the throttle amount exceeds 90%.
(Note: You need to re-standardize the RPM after replacing the motor, blades, body frame or adjusting the gear ratio.)

1.3. In “Heli Store Governor” mode, if you fly your aircraft with another battery pack that has poor discharge capability after the RPM standardization (with a pack which has good discharge capability), the pack has poor discharge capability may be get damaged.

2. **LiPo Cells:** the ESC will automatically calculate the number of LiPo cells you have plugged in as per the “3.7V/Cell” rule if “Auto Calculate” is selected. Or user can set this item manually.

3. **Voltage Cutoff Mode:** the ESC will gradually reduce the output to 50% of the full power in 3 seconds after the voltage cutoff protection is activated, if soft mode is selected. It will immediately cut off all the output when hard mode is selected.

4. **Cutoff Voltage:** 2.7V-3.7V (custom), 3.3V (default).

5. **BEC Output:** 5-8V (adjustable), 0.1V (step), 7.4V (default).

6. **Start-up Time:** 4-25s (adjustable), 1s (step), 15s (default).

7. **Governor Parameter P:** Control the ESC maintaining the stability of the current motor speed.

8. **Governor Parameter I:** Control the dynamic response. To be specific, control the supplement extent when the actual motor speed is below expectation. If you choose a very big value, then the supplement may be too much. If select a very small value, then the supplement may not sufficient.

9. **Auto Restart Time:** the ESC will cut off its output when the throttle amount is between 25% and 40%. If you increase the throttle amount to above 40% within preset time period (0-90s), the motor will rapidly start up and accelerate to the speed (in 1s) corresponds to the specific throttle amount, complete the shutdown and restart up.If you move the throttle stick to over 40% beyond the preset time period, the ESC will enter the soft start-up process. (Note: This function only effects in “Heli Governor Elf/Store” mode.)

10. **Timing:** 0-30° (adjustable), 1° (step) , 15° (default).

11. **PWM Frequency:** 8KHz/15KHz/20KHz/30KHz (adjustable), 30KHz (default).

12. **Brake Force:** 0-100% (adjustable), 1% (step), 0 (default).

13. **Motor Rotation:** CW/CCW. User can adjust this item via a multifunction LCD program box.

14. **Restart Acceleration Time:** 1s/1.5s/2s/2.5s/3s (adjustable), 2s (default). This item controls the time the motor accelerates from standstill to full speed after the Auto Restart is triggered and your helicopter restarts its flight.

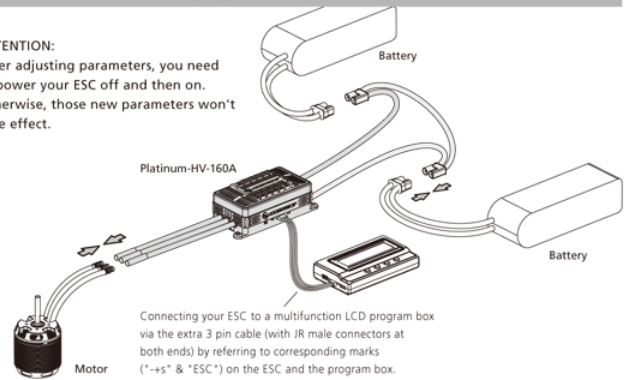
15. **Con. Freewheel:** User can decide this function “Activated” or “Disabled” in “Fixed Wing” mode or in “Heli (Linear Throttle Response)” mode. This item has been preset to “Activated” and cannot be adjusted in “Heli (Elf Governor/Store Governor) mode. This function can brings better throttle linearity.

05 How to Program Your ESC

With a multifunction LCD program box

ATTENTION:

After adjusting parameters, you need to power your ESC off and then on. Otherwise, those new parameters won't take effect.



ESC programming

Connect the LCD program box and a battery to your ESC as shown above.

Press the “OK” button to connect the program box to your ESC. The current firmware version will show up after the program box is successfully connected to the ESC.

Press the “ITEM” button to browse all the programmable items, and then press the “OK” button to enter any programmable item you want to set.

Press the “Value” button to browse all parameter values after entering the specific programmable item.

Press the “OK”button to save the new parameter value you just selected.

With a WiFi Module: Please refer to the user manual of the Hobbywing WiFi module.

06 Data Checking and Normal Start-up Process

Data Checking

The ESC will record the standardized RPM, minimum voltage, maximum current, maximum temperatures of the current flight but won't save these data, so you need to keep the ESC on if you want to check the information of the current flight.

Connect the LCD program box and a battery to your ESC as shown above.

Press the “OK” button to connect the program box to your ESC. The current firmware version will show up after the program box is successfully connected to the ESC.

Press the “R/P” button to browse all running information relates to the ESC.

Notes: 1. you can only check the standardized RPM in “Heli Store Governor” mode, this record won't disappear after you turn off the ESC.

2. The recorded revs are electric revs. If the electric rev is R, the actual rev of blades=R ÷ Motor Poles ÷ 2 ÷ Gear Ratio x throttle amount(%).

Normal Start-up Process

Turn on the transmitter, and then move the throttle stick to the bottom position.

After connected to a battery, the ESC will emit “J 123” indicating it's normally powered on.

The motor will emit several beeps to indicate the number of LiPo cells.

The motor emits a long beep indicating the ESC is ready to go.

During the normal running process, the Blue LED on the ESC will turn solid after the start-up completes. The Red LED will also come on at full throttle and it dies out at partial throttle. (Please refer to the following form for detailed instructions.)

07 Troubles & Status LEDs

Trouble(s)	Possible Causes	LED Status
Over-current protection is activated.	The current is above 350A.	Red LED turns on solid.
Throttle Signal Loss.	No throttle signal is received for over 0.25 second.	Red LED blinks once and repeats.
Abnormal BEC voltage.	BEC voltage is below/above than 3V/9V	Red LED blinks 4 times and repeat.
Abnormal power voltage.	Power voltage is not within 18.5-51.8V (or 6-14S).	Red LED blinks twice and repeat.
Thermal shutdown protection is activated.	The ESC temperature is over 110°C (230°F)	Blue LED blinks once and repeats.
Low voltage cutoff protection is activated.	The voltage goes below the cutoff voltage.	Blue LED blinks twice and repeat.

Warning Tone	Possible Issue
“Beep beep, beep beep” (The interval is 1 sec)	Abnormal input voltage.
“Beep-beep-” (The short, single beep that repeats rapidly)	The throttle stick isn't moved to the bottom position (before use) or the throttle range is too narrow.

Multiple Protections	How to Protect
Start-up Protection	The ESC will monitor the motor speed during the start-up process. When the speed stops increasing or the speed increase is not stable, the ESC will take it as a start-up failure. At that time, if the throttle amount is less than 15%, the ESC will automatically try to restart up; if it is larger than 15%, you need to move the throttle stick back to the bottom position and then restart up the ESC.
Thermal Shutdown Protection	The ESC will gradually reduce the output but won't cut it off completely when the ESC temperature goes above 230°F. For ensuring the motor can still get some power and won't cause crashes, so the maximum reduction is about 50% of the full power. The ESC will gradually resume its maximum power after the temperature lowers down. In addition, the ESC temperature cannot exceed 158°F when it's powered on. Otherwise, it cannot be started up. (Here we are describing the ESC's reaction in soft cutoff mode, while if in hard cutoff mode; it will immediately cut off the power.)
Throttle Signal Loss Protection	When the ESC detects loss of signal for over 0.25 second, it will cut off the output immediately to avoid an even greater loss which may be caused by the continuous high-speed rotation of propellers or rotor blades. The ESC will resume the corresponding output after normal signals are received.
Overload Protection	The ESC will cut off the power/output or automatically restart itself when the load suddenly increases to a very high value. Possible cause to sudden load increase is that propellers are blocked.
Over-current Protection	The ESC will cut off the power when the current gets close to the short circuit current (of 350A). This protection may be activated by the burnt motor or some others.
BEC Safety Protection	The internal BEC circuit and CPU power supply circuit are separated. The BEC will keep its normal output and ensure relevant devices like steering servos are functioning normally when the over-current protection is activated or MOSFET(s) inside the ESC is/are burnt, this can protect your aircraft from possible crash.